

Some characteristics of an equity security next-year impairment

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Abstract

In this paper, we propose some characteristics of next-year impairments in a generic Black & Scholes framework, with one equity security, and under IFRS rules. We derive expression for the probability of impairment event for an equity-security recognized in the available-for-sale (AFS) category. Our decomposition of this event is also useful to retrieve barrier options valuation methods. From there, we obtain an explicit formula for the first moment of impairment value and its cumulative distribution function, as well as sensitivities. Numerical studies are carried out on concrete securities. We also study a mean-preserving one-criterion proxy used by some insurance practitioners for the next-year impairment losses and discuss its relevance. More generally, our study paves the way for applications of financial mathematics techniques to accounting issues related to impairments in the IFRS framework.

1 Introduction

Most of financial institutions publish their financial reporting under the International Financial Reporting Standards (IFRS). It is even mandatory for companies which are listed at stock exchange or have issued bonds within the European Union.

Due to the present standards, these companies measure financial assets at fair value. As a matter of fact, even if bonds are eligible to the amortized

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cost through the Held-To-Maturity (HTM) category, the restrictions on this category have led financial institutions (and especially insurance company) to parsimoniously use this ability. As a consequence most of insurance companies financial assets are categorized as Available-For-Sale (AFS) and so measured at fair value.

In this category, financial assets are measured at fair value in the balance sheet. Nevertheless paragraph 55 of IAS 39 states that *a gain or loss on an available-for-sale financial asset shall be recognized in other comprehensive income (OCI), except for impairment losses and foreign exchange gains and losses, until the financial asset is de-recognized.* This constitutes the main difference with the Held-For-Trading (HFT) category which consists in a measurement at Fair Value through profit or loss. This latest category is much less used by financial institutions due to the volatility it generates in the result.

Table 1 shows the preponderance of this category among insurance companies.

Table 1. Some figures about insurance companies investments in 2011.

(Mds €)	Allianz	Axa	CNP Assurances	Generali
Balance Sheet Size	641.472	730.085	321.011	423.057
Total equity	47.253	50.932	13.217	18.120
AFS Assets	333.880	355.126	231.709	175.649
AFS (Funds and equity securities)	26.188	20.636	27.618	20.53

N.B. Figures are extracted from the 2011 reference document of each company.

As along as a financial asset classified as AFS belongs to a company, any gains or losses on this asset are not recognized in profit or loss. Unless any impairment losses occur. In such a case, IAS 39 states that *the amount of the cumulative loss that is reclassified from equity to profit or loss (...) shall be the difference between the acquisition cost (net of any principal repayment and amortization) and current fair value, less any impairment loss on that financial asset previously recognized in profit or loss.*

Paragraph 59 of IAS 39 states that *A financial asset (...) is impaired and impairment losses are incurred if, and only if, there is objective evidence of impairment as a result of one or more events that occurred after the initial recognition of the asset (a "loss event") and that loss event (or events) has an impact on the estimated future cash flows of the financial asset (...) that*

can be reliably estimated. This principle is completed in paragraph 61 for equity instruments : *A significant or prolonged decline in the fair value of an investment in an equity instrument below its cost is also objective evidence of impairment.*

To resume, if for debt instruments classified as AFS, the impairment criterion is based on a loss event (this leads to consider the present impairment methodology for such instruments as "incurred approach" by opposition of an "expected approach"), IAS 39 gives a more precise double-criterion for considering impairment losses for an equity instrument. It is important to note that the two conditions do not necessarily to be concomitantly met in order to lead to an impairment loss (it is the case in some local accounting standards such as the French ones). This has been confirmed by an IFRIC¹ Update of July 2009. Moreover for those instruments, any impairment losses shall not be reversed through profit or loss (see Paragraph 69).

This situation can be resumed by Table 2 (cf. Thérond (2012)).

Table 2. Overview of IAS 39 impairment disposals.

Category	HTM	AFS	HFT
Eligible securities	Bonds	Bonds	Others (stock, funds, etc.) Everything
Valuation	Amortized cost	Fair Value (through OCI)	Fair Value through P&L
Impairment principle	Event of proven loss	Event of proven loss	Significant or prolonged fall in the fair value NA
Impairment trigger	Objective evidence resulting from an incurred event (cf. IAS 39 §59)		Two criteria (non-cumulative; Cf. IFRIC Update of July 2009) : significant or prolonged loss in the FV NA
Impairment Value	Difference between the amortized cost and the revised value of future flows discounted at the original interest rate	In result : difference between reported value (before impairment) and the FV NA	
Reversal of the impairment	Possible in specific cases	Possible in specific cases	Impossible NA

As a consequence with the present standard, most of impairment losses on AFS financial assets come from equity instruments.

¹ International Financial Reporting Standards Interpretations Committee.

Table 3 compares, for some insurance companies, their 2011 result and the losses from AFS funds and equity securities impairment. N.B. The figures are extracted from the 2011 reference document of each company.

Table 3. Some figures about insurance companies investments in 2011 (continued).

(M€)	Allianz	Axa	CNP Assurances	Generali
Result	2804	4516	1141	1153
Impairment losses on AFS funds and equity securities	-2487	-860	-1600	-781

We see that these impairment losses are far from being negligible compared to the result of these insurers. Also in this paper, we focus on equity instruments classified as available for sale.

The following questions are of interest for a company which holds equity instruments classified as AFS: what is the probability that an impairment occurs before the next financial reporting? What is the expected amount of such an impairment loss? What is its distribution function? To which parameters is this amount the most sensitive?

After giving an overview of practices of financial institutions to consider what kind of decline leads to an impairment loss, the aim of our paper is to provide some answers to the above questions in the Black & Scholes model². The two criteria and the form of the impairment losses are similar to those of the (probabilistic) payoff of a sum of three financial options. Among them the first one corresponds to a classical European put option (cf. Hull (2011)). The two others are in the family of the barrier options: the rear-end up-and-out put option (cf. Hui (1997)).

Using results about barrier options from Hui (1997), Chuang (1996) and Carr and Chou (1997), we give an analytical formula of the expectation of the next-year impairment losses for any equity security (even previously impaired) in the Black & Scholes model. Moreover we compute the cumulative distribution function of the next year impairment losses which enables a Chief Financial Officer (CFO) and a Chief Risk Officer (CRO) to measure the risk of any deviation in the profit or loss resulting from any impairment of such a security. For each characteristic, we will give sensitivities on parameters. These results

² Even if this model is far from being perfect, it is still widely used, sometimes with modifications like stochastic volatility or stochastic interest rates. As our goal is to study impairments and not to build a more reliable risky asset model, we believe that this is not a big problem.

are illustrated on real securities from the French stock market. In the final part of our work, we find a mean-preserving relation between the parameters of the impairment criteria and those of a simplified version (using only the significant decline criterion) that is easier to compute. Some practitioners argue that such a proxy could be used in order to get a more simple formula. We show that such an proxy is only relevant when large impairment losses already incurred in the previous financial reporting statements, because differences between the results of the two methods are important when no large impairment has occurred yet. In order to get a more readable paper, the proofs of the results are given in the Appendix. Apart from solving this particular issue, another goal of this paper is to demonstrate how financial mathematics techniques can be applied to IFRS accounting problems, including impairment related ones.

2 Impairment of equity securities

The aim of this section is to give an overview of how financial institutions such as banks and insurance companies interpret Paragraph 61 of IAS 39 in order to determine the parameters to consider a *significant* or *prolonged* decline which leads to an impairment loss for an equity security.

A study of the auditing company Grant Thornton (2009) indicates that these criteria have fallen within the following ranges:

- *significant* between 20% and 30%
- *prolonged* between 9 and 12 months.

Nevertheless, as we can see in Table 4, these parameters are very volatile among financial institutions. Moreover some of them consider a third criterion which embrace both significant and prolonged decline: a prolonged decline under a significant fall in fair value since the acquisition time. We can observe that a wide range of criterion are practically used. Obviously the greater the *significant* (resp. the *prolonged*) parameter is, the later an impairment loss occurs and the greater the potential impaired amount may be. If one positions impairment risk in a risk map (whose axes correspond to probability of occurrence and expected severity if event occurs), it is going to lie close to different axes for different insurers (for equivalent previous impairments): for AXA it would be closer to the first axis, because this company tends to recognize impairments much faster (after a 20% decrease or a 6-month prolonged decline) than Generali, who recognizes impairments only after a 50% decrease or a 3-year prolonged decline. In Generali risk map, impairment risk would be closer to the second axis, because the probability of impairment is much smaller, but if this happened, the impairment amount would be much higher. Decision makers need some quantitative analysis to complement this qualita-

tive analysis in order to set up their trigger parameters. The computations we present in this paper enable CFO's and CRO's to quantify impairment risk and to choose their appropriate thresholds. In the numerical applications section, we carry out some sensitivity analysis and also provide concrete numbers for probability of impairment and expected severity given that event occurs for Axa and Generali trigger parameters in different stock price evolution and past impairment scenarios. The additional criterion that some companies consider seems like the trigger given by some local GAAP (French GAAP for example for which a continuously fall of 20 % or 30 % during the last 6 months leads to an impairment loss).

Table 4. Impairment parameters used by some insurance companies in 2011.

Company	<i>Significant</i> parameter	<i>Prolonged</i> parameter (months)	Supplementary criterion ³
Allianz	0.2	9	
Axa	0.2	6	
BNP Paribas	0.5	24	0.3 12 months
CNP	0.5	36	
Crédit Agricole	0.4	∅	0.2 6 months
Generali	0.5	36	
Groupama	0.5	36	
ING	0.25	6	
Scor	0.5	24	0.3 12 months
Société Générale	0.5	24	

N.B. The figures are extracted from the 2011 reference document of each company.

3 Notation and model

The aim of this section is to give a mathematical framework in order to deal with the properties of the (probabilistic) next-year impairment loss of an eq-

³ This supplementary criterion has to be read in the following manner: $x\%|y$ means that there is an impairment presumption if the *fair value* is more than $x\%$ below the carrying amount for more than y consecutive months before the financial reporting date.

uity security classified as AFS.

3.1 Notation

Let us denote by $S = (S_t)_{0 \leq t}$ the stock price at time t . We denote the acquisition date by $t_a \geq 0$. We assume that we want to forecast next year impairments at some time $t \geq t_a$. Hereafter, we introduce all quantities that constitute the information of the Chief Financial Officer at time t (present).

With these notation, S_{t_a} is the acquisition cost of the stock and S_t is the fair value of the stock at time t .

Let us denote by $\Lambda(S, t_a, t)$ the cumulative results obtained through the sum of profit and loss starting at time t_a until now:

$$\Lambda(S, t_a, t) = \sum_{s=[t_a]+1}^t \lambda(S, t_a, s). \quad (1)$$

Remark 1 *The above sum starts at the first integer valued date after the acquisition. In fact it is more general than that because times of annual accounts are not necessary integers. This detail has no influence on the results.*

As there will be no possible confusion, we choose to use Λ_t .

Let us denote by $\Omega(S, t_a, t)$ the cumulative unrealized gains and losses deferred in Other Comprehensive Incomes (OCI) since t_a .

We have the balance sheet equilibrium property:

$$S_t - S_{t_a} = \Omega(S, t_a, t) + \Lambda_t. \quad (2)$$

The unrealized gains and losses have to be reported either on past profit and loss or on OCI, since the financial asset is measured at fair value in the balance sheet.

To summarize, at time t , information available for the CFO corresponds to $\mathcal{F}_t = \{S_{t_a}, S_t, \Lambda_t\}$. Using this, we would like to forecast the following year impairments. According to what the CFO knows, probabilities have to be evaluated conditionally to information \mathcal{F}_t at time t .

3.2 Modeling the impairment triggers and losses

The aim of this subsection consists in modeling the impairment trigger and the resulting losses if any. We divide each impairment process into two steps. The first one deals with the (non-cumulative) couple of criteria on the fall (*significant* or *prolonged*).

The trigger for an impairment at time $t + 1$ can be written as:

$$\begin{cases} S_{t+1} \leq (1 - \alpha)S_{t_a}, \text{ or;} \\ \forall u \in]t + 1 - s, t + 1], S_u \leq S_{t_a}, \end{cases} \quad (3)$$

where the parameters α and s are determined by the company.

- Parameter $\alpha \in]0, 1[$ represents the relative level of fall in fair value since the acquisition date corresponding to *significant* decline.
- Parameter $0 < s < 1$ represents the minimum period before the financial reporting date that leads to consider that the decline is *prolonged*.

The second step is to determine if an impairment really occurs. For that, we have to test the following condition: $S_{t+1} \leq S_{t_a} - \Lambda_t$. Finally, for each t , we define J_{t+1} as the Bernoulli random variable that takes value 1 if some impairment occurs at time $t + 1$. This occurs if both the trigger condition is satisfied and $\{S_{t+1} \leq S_{t_a} - \Lambda_t\}$.

Then, if an impairment is recognized, its value is denoted by λ_{t+1} and is equal to $S_{t_a} - \Lambda_t - S_{t+1}$. Without loss of generality, we have $\lambda_{t+1} = (S_{t_a} - \Lambda_t - S_{t+1})^+$ or, as for a European *put* option, $\lambda_{t+1} = (K_t - S_{t+1})^+$, with $K_t = S_{t_a} - \Lambda_t$.

3.3 Stock price evolution

Let $(W_t)_{0 \leq t}$ be a standard Brownian motion. Let $(S_t)_{0 \leq t}$ be the price process of some asset in the Black-Scholes model: for $0 \leq t$, we have, under the real-world probability,

$$\frac{dS_t}{S_t} = \mu dt + \sigma dW_t, \quad (4)$$

where $(W_t)_{t \geq 0}$ is a standard Brownian motion. We denote the risk-free interest rate by r .

4 Characteristics of the next-year impairment

The aim of this section is to provide in the Black & Scholes framework the main characteristics of the (potential) next year impairment losses. The main results are, for the next year reporting:

- the probability that some impairment occurs,
- the expectation of impairment losses,
- the cumulative distribution function (c.d.f.) of impairment losses.

These results enable a CFO to analyze both the next year losses resulting from holding such an investment categorized as AFS and to determine some risk indicators in order to manage the risk of an impairment loss resulting from this equity securities. More precisely, the two first indicators enable the CFO and the CRO to position impairment risk on a risk map (chart whose coordinates correspond to probability of occurrence and expected severity of events). The last indicator enables them to take impairment risk into account in internal risk models, or to deal with the multi-period case by induction. Of course, if one knows the c.d.f., one knows everything, including the two first indicators. But it is much longer to compute the c.d.f. than the two first quantities, and it would be painful, and numerically complex to retrieve the expected value of impairments by integration of the survival function. Consequently, we analyze the three risk indicators separately and provide formulas and computation scheme for each of them.

4.1 Impairment probability

We express the probability to recognize an impairment in one year conditionally to \mathcal{F}_t , $\mathbb{P}[J_{t+1}|\mathcal{F}_t] = \mathbb{P}_t[J_{t+1}]$. Let us start by re-writing J_{t+1} :

$$J_{t+1} = (S_{t+1} \leq (1 - \alpha)S_{t_a}, S_{t+1} \leq K_t) \cup \left(\max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a}, S_{t+1} \leq K_t \right).$$

Then, it is easy to obtain, introducing $m_t = \min((1 - \alpha)S_{t_a}, K_t)$:

$$\begin{aligned} \mathbb{P}_t[J_{t+1}] &= \mathbb{P}_t[S_{t+1} \leq m_t] + \mathbb{P}_t \left[\max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a}, S_{t+1} \leq K_t \right] \\ &\quad - \mathbb{P}_t \left[\max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a}, S_{t+1} \leq m_t \right]. \end{aligned}$$

The next step is to retrieve an expression using the drifted Brownian motion and the joint law of its current maximum and its value. Details are provided in Appendix A. We are then able to enunciate the following theorem:

Theorem 1 (Impairment probability) *The probability to recognize an impairment at future time $t + 1$, given the information \mathcal{F}_t at time t , is given by*

$$\begin{aligned} \mathbb{P}_t [J_{t+1}] = & \left(\frac{S_{t_a}}{S_t} \right)^{k_1-1} [\Psi_\rho (C, D(K_t)) - \Psi_\rho (C, D(m_t))] \\ & + \Phi (-A(K_t)) + \Psi_\rho (B, A(K_t)) - \Psi_\rho (B, A(m_t)), \end{aligned} \quad (5)$$

where, for $x \in \{m_t, K_t\}$,

- $A(x) = \frac{\ln(S_t/x)+\mu}{\sigma} - \frac{\sigma}{2}$, $A'(x) = A(x) + \sigma$,
- $B = \frac{\ln(S_t/S_{t_a})+\mu(1-s)}{\sigma\sqrt{(1-s)}} - \frac{\sigma\sqrt{(1-s)}}{2}$, $B' = B + \sigma\sqrt{(1-s)}$,
- $C = \frac{\ln(S_{t_a}/S_t)+\mu(1-s)}{\sigma\sqrt{(1-s)}} - \frac{\sigma\sqrt{(1-s)}}{2}$, $C' = C + \sigma\sqrt{(1-s)}$,
- $D(x) = \frac{\ln(S_{t_a}^2/S_t x)+\mu}{\sigma} - \frac{\sigma}{2}$, $D'(x) = D(x) + \sigma$,
- $k_1 = \frac{2\mu}{\sigma^2}$,

Φ denotes the c.d.f. of a standard normal distribution, and Ψ_ρ is the bivariate normal distribution function: for all x, y , $\Psi_\rho(x, y) = \mathbb{P}_t [X \leq x, Y \leq y]$ where (X, Y) is a Gaussian vector with standard marginals and correlation ρ .

The proof is given in the Appendix.

Remark 1 *This is also the probability to have non-null impairment:*

$$\mathbb{P}_t [J_{t+1}] = \mathbb{P}_t [\lambda_{t+1} \neq 0].$$

Theorem 2 (Probability sensitivities) *The impairment probability is decreasing in α , μ , Λ and s . Moreover, it is convex in α , μ and s .*

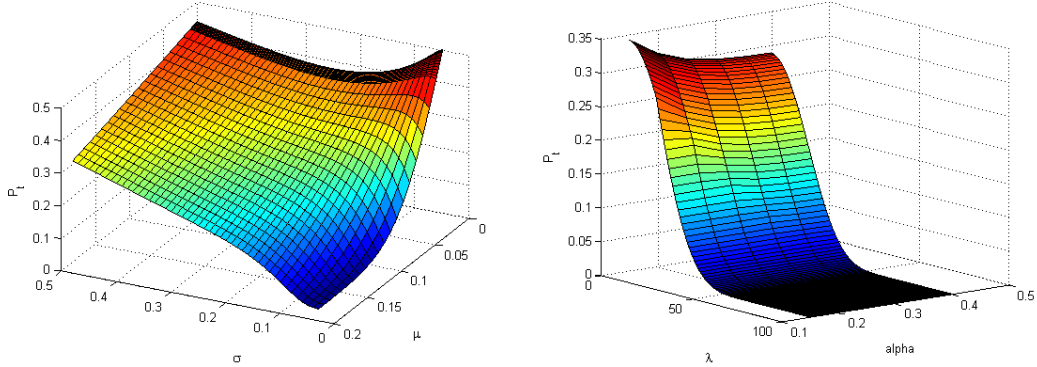


Figure 1. Probability to recognize an impairment next year as a function of μ and σ (left), and of Λ and α (right).

Remark 2 *On Figure 1, we observe that the probability to recognize an impairment next year is neither globally convex in σ , nor globally concave. Ac-*

tually, we observe some (local) convexity in σ when μ is close to 0, and some (local) concavity for large values of μ . Moreover, there is an area where the first derivative of the sensitivity is not monotonous.

4.2 Expectation of the next-year impairment loss

The impairment value can be seen as a payoff of some complex option. Consequently, in the sequel, we decompose the payoff, in order to retrieve some simpler and known expressions. We denote \mathbb{E}_t instead of $\mathbb{E}[\cdot|\mathcal{F}_t]$ for simplicity, as we have done for probabilities.

Proposition 2 *The payoff we are interested in is*

$$\lambda_{t+1} = (K_t - S_{t+1})^+ \mathbf{1} \left\{ \max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a} \cup S_{t+1} \leq (1-\alpha)S_{t_a} \right\}, \quad (6)$$

with $K_t = S_{t_a} - \Lambda_t$. We have

$$\lambda_{t+1} = X_{t+1} + Y_{t+1} - Z_{t+1},$$

with

- $X_{t+1} = (K_t - S_{t+1})^+ \mathbf{1} \{ \max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a} \}$,
- $Y_{t+1} = (K_t - S_{t+1})^+ \mathbf{1} \{ S_{t+1} \leq (1-\alpha)S_{t_a} \}$,
- and $Z_{t+1} = (K_t - S_{t+1})^+ \mathbf{1} \{ \max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a} \} \cdot \mathbf{1} \{ S_{t+1} \leq (1-\alpha)S_{t_a} \}$.

Remark 3 *These three terms can be interpreted as payoffs of options with underlying asset S . The first one corresponds to a rear-end up-and-out put option (as it appears in Hui (1997)), the second one to a classic European put option, and the third one is a bit more complicated: Z_{t+1} corresponds to the sum of the payoff of a rear-end up-and-out put option and of a compensating quantity. All the details can be found in Appendix B.*

Finally, again with $m_t = \min((1-\alpha)S_{t_a}, K_t)$, one may obtain the expected value of next year impairment.

Theorem 3 (Impairments expectation) *The expectation of next-year im-*

pairment, given the information \mathcal{F}_t at time t , is given by

$$\begin{aligned}
\mathbb{E}_t[\lambda_{t+1}] &= S_t e^\mu \left(\frac{S_{t_a}}{S_t} \right)^{k_1-1} [\Psi_{-\rho}(C', -D'(K_t)) - \Psi_{-\rho}(C', -D'(m_t))] \\
&\quad + S_t e^\mu [\Psi_\rho(-B', -A'(m_t)) - \Phi(-A'(m_t)) - \Psi_\rho(-B', -A'(K_t))] \\
&\quad + K_t [\Psi_\rho(-B, -A(K_t)) + \Phi(-A(m_t)) - \Psi_\rho(-B, -A(m_t))] \\
&\quad + (K_t - m_t) \left(\frac{S_{t_a}}{S_t} \right)^{k_1-1} [\Phi(-D(m_t)) - \Psi_\rho(-C, -D(m_t))] \\
&\quad - K_t \left(\frac{S_{t_a}}{S_t} \right)^{k_1-1} \Psi_{-\rho}(C, -D(K_t)) + m_t \left(\frac{S_{t_a}}{S_t} \right)^{k_1-1} \Psi_{-\rho}(C, -D(m_t)),
\end{aligned} \tag{7}$$

where all constant numbers, variables and parameters are defined in Theorem 1 Page 10.

Corollary 4 *We can interpret the impairment as a financial product. Consequently, the "price" of this option - namely the expectation under risk neutral probability \mathbb{Q} (cf. Hull (2011)) of discounted value of the next-year impairment loss - is given by :*

$$\begin{aligned}
\mathbb{E}_t^{\mathbb{Q}}[e^{-r}\lambda_{t+1}] &= S_t \left(\frac{S_{t_a}}{S_t} \right)^{\tilde{k}_1-1} [\Psi_{-\rho}(\tilde{C}', -\tilde{D}'(K_t)) - \Psi_{-\rho}(\tilde{C}', -\tilde{D}'(m_t))] \\
&\quad + S_t [\Psi_\rho(-\tilde{B}', -\tilde{A}'(m_t)) - \Phi(-\tilde{A}'(m_t)) - \Psi_\rho(-\tilde{B}', -\tilde{A}'(K_t))] \\
&\quad + K_t e^{-r} [\Psi_\rho(-\tilde{B}, -\tilde{A}(K_t)) + \Phi(-\tilde{A}(m_t)) - \Psi_\rho(-\tilde{B}, -\tilde{A}(m_t))] \\
&\quad + (K_t - m_t) e^{-r} \left(\frac{S_{t_a}}{S_t} \right)^{\tilde{k}_1-1} [\Phi(-\tilde{D}(m_t)) - \Psi_\rho(-\tilde{C}, -\tilde{D}(m_t))] \\
&\quad - K_t e^{-r} \left(\frac{S_{t_a}}{S_t} \right)^{\tilde{k}_1-1} \Psi_{-\rho}(\tilde{C}, -\tilde{D}(K_t)) \\
&\quad + m_t e^{-r} \left(\frac{S_{t_a}}{S_t} \right)^{\tilde{k}_1-1} \Psi_{-\rho}(\tilde{C}, -\tilde{D}(m_t)),
\end{aligned} \tag{8}$$

where, for $x \in \{m_t, K_t\}$,

- $\tilde{A}(x) = \frac{\ln(S_t/x)+r}{\sigma} - \frac{\sigma}{2}$, $\tilde{A}'(x) = \tilde{A}(x) + \sigma$,
- $\tilde{B} = \frac{\ln(S_t/S_{t_a})+r(1-s)}{\sigma\sqrt{1-s}} - \frac{\sigma\sqrt{1-s}}{2}$, $\tilde{B}' = \tilde{B} + \sigma\sqrt{1-s}$,
- $\tilde{C} = \frac{\ln(S_{t_a}/S_t)+r(1-s)}{\sigma\sqrt{1-s}} - \frac{\sigma\sqrt{1-s}}{2}$, $\tilde{C}' = \tilde{C} + \sigma\sqrt{1-s}$,
- $\tilde{D}(x) = \frac{\ln(S_{t_a}^2/S_t x)+r}{\sigma} - \frac{\sigma}{2}$, $\tilde{D}'(x) = \tilde{D}(x) + \sigma$,
- $\tilde{k}_1 = \frac{2r}{\sigma^2}$,

Φ is the c.d.f. of a standard normal distribution, $\rho = \sqrt{1-s}$ and Ψ_ρ is as

above.

Theorem 5 (Expectation sensitivities) *The impairment value is decreasing in α , μ , Λ and s , and increasing in σ . Moreover, it is convex in α , μ , σ and Λ , and concave in s .*

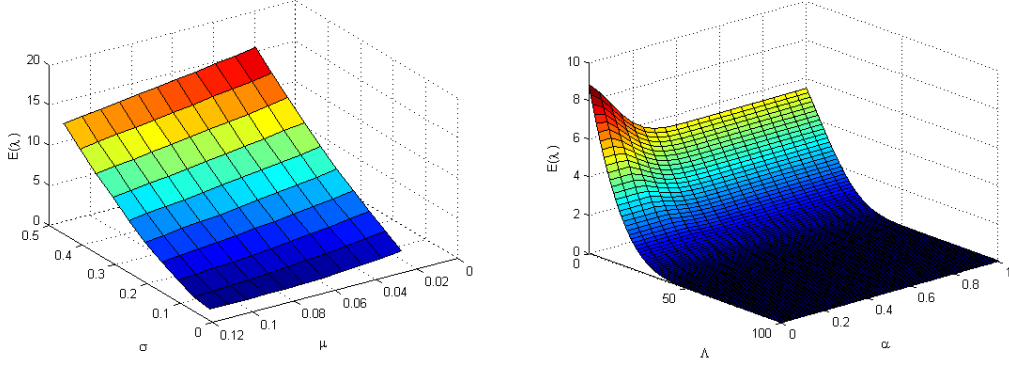


Figure 2. Average impairment next year as a function of μ and σ (left), and of α and Λ (right).

The expected next year impairment is illustrated in Figure 2 as a function of some key parameters. One can notice that its structure is quite simple in terms of μ and σ , but more complex in terms of Λ and α as non-linearity comes from exotic optional-type behavior.

4.3 Distribution of the next-year impairment

In order to give a more complete panel of characteristics of the next-year impairment, we have to study the law of its value. This is particularly important for future extensions to multi-year models. In the following section, we are able to give the cumulative distribution function of next-year impairment.

Theorem 6 (Distribution function of impairments) *The cumulative distribution function of the next-year impairments, given the information \mathcal{F}_t at time t , is given by*

$$\mathbb{P}_t[\lambda_{t+1} \leq l] = \begin{cases} (1 - \mathbb{P}_t[J_{t+1}]) + \Phi(A(K_t - l)) - \Phi(A(K_t)) \\ + \left(\frac{S_{t_a}}{S_t}\right)^{k_1 - 1} [\Psi_\rho(C, D(K_t)) - \Psi_\rho(C, D(K_t - l))] \\ + \Psi_\rho(B, A(K_t)) - \Psi_\rho(B, A(K_t - l)) & , 0 \leq l \leq K_t - m_t, \\ \Phi(A(K_t - l)) & , K_t - m_t < l \leq K_t, \end{cases} \quad (9)$$

where all constant numbers, variables and parameters are defined in Theorem 1 Page 10.

In another way, we have

$$\mathbb{P}_t[\lambda_{t+1} \leq l] = \begin{cases} \Phi(A(K_t - l)) + \Psi_\rho(B, A(m_t)) - \Psi_\rho(B, A(K_t - l)) \\ + \left(\frac{S_{t_a}}{S_t}\right)^{k_1 - 1} [\Psi_\rho(C, D(m_t)) - \Psi_\rho(C, D(K_t - l))] \\ \Phi(A(K_t - l)) \end{cases} \begin{cases} , 0 \leq l \leq K_t - m_t, \\ , K_t - m_t < l \leq K_t. \end{cases} \quad (10)$$

The proof is given in the Appendix.

5 Illustration on real data

We now want to study numerically next year impairment characteristics in concrete cases.

5.1 Data description

We have chosen stocks of French market CAC40: **BNP Paribas**, **Bouygues**, **Carrefour**, **Pernod Ricard** and **Total**.

The dataset consists of daily quotations starting at the fourth of January, 2010, and ending at the thirty-first of December, 2012. It almost corresponds to 3 entire years of data. These quotations are used in order to calibrate model parameters (volatility and drift) and give initial and terminal values. This period was impacted by the financial crisis. As volatilities may be higher than in normal periods, we expect to observe more important impairments. Annual volatilities are provided by the website *Small Caps Vision*. The value of μ is obtained by adding a constant drift (3%) to the volatility: if the volatility is σ , then $\mu = \log(1 + 3\%) + \sigma^2/2$. The buying value S_{t_a} is the quotation of the stock at the date 01/4/2010. Those figures are summarized in Table 5.

Table 5. Used data.

	S_{t_a} (€)	Annual volatility	μ
BNP Paribas	57.24	48.92%	14.92%
Pernod Ricard NV	60.83	22.80%	5.56%
Bouygues	37.02	31.56%	7.94%
Carrefour	29.7016	33.80%	8.67%
Total	45.795	22.61%	5.51%

The first step in this study is to study realized impairments in Table 6. Indeed, we apply our impairment criterion on the close values of the stocks. Remark that this is not perfect, because we are processing on discrete values and the barrier (in the prolonged criteria of impairment) has to be continuous, but this has minor effect on our results. Note that some stocks like BNP Paribas and Carrefour feature consequent impairments, while some others like Pernod Ricard do not feature any impairment in this particular case. As impairments have to be recognized securities by securities, part of the investment diversification effect is not fully recognized in the IFRS framework.

Table 6. Past impairment losses.

Impairments for the year :	2010	2011	2012	Total
BNP Paribas	9.63	17.26	0	26.89
Pernod Ricard NV	0	0	0	0
Bouygues	4.76	7.92	1.94	14.62
Carrefour	0	12.0916	0	12.0916
Total	6.145	0.15	0.49	6.785

5.2 Next year impairment for various past impairment cases

After this step, at time $t = 12/31/2012$, we now compute the probability $\mathbb{P}_t[J_{t+1}]$ to recognize an impairment next year, the expectation $\mathbb{E}_t[\lambda_{t+1}]$ of next year impairment, as well as different Value-at-Risks at levels 80%, 95% and 99.5%. For the sake of brevity we only present results for Total in Table 7. We use standard trigger criteria, i.e. $\alpha = 0.3$ and $s = 0.5$. We also use market parameters given previously and the historical buying value S_{t_a} . We artificially vary Λ , set to 5%, 10%, 50% and 75% of the buying value S_{t_a} (that do not correspond to the history of realized impairment between t_a and t) in order to study next year impairments in different situations. When $\Lambda_t = 2.28975$, at least one small impairment occurred because of the prolonged depreciation criterion. The current price S_t is now much lower than S_{t_a} and $S_{t_a} - \Lambda_t$, but still above $0.7S_{t_a}$. It means in particular that the stock price crossed level S_{t_a} in the time interval $[t - 0.5; t)$: the stock price went severely down during the last six-month period before t . In this case, the probability to recognize an impairment at time $t + 1$ is larger than $1/2$, and the average impairment $\mathbb{E}_t[\lambda_{t+1}]$ is approximately equal to 4. When $\Lambda_t = 22.8975$, the probability to recognize an impairment next year is very low (smaller than 80bps), and $\mathbb{E}_t[\lambda_{t+1}]$ is very small too. This is because at least one impairment has been recognized in the past due to the significant depreciation criterion. The last impairment when the stock price was much lower (below 23) than the current

price S_t . The probability that S_{t+1} falls again below 23 is very small.

Table 7. Results for Total.
Total. $S_{t_a} = 45.795$

S_t	Λ	$\mathbb{P}_t [J_{t+1}]$	$\mathbb{E}_t [\lambda_{t+1}]$	$VaR(80\%)$	$VaR(95\%)$	$VaR(99.5\%)$
38.42	2.28975	0.5509	4.0699	10.7697	16.2236	21.402
	4.5795	0.5075	3.3007	8.4799	13.9338	19.1123
	22.8975	0.0078	0.0124	0	0	0.7943
	34.34625	0	0	0	0	0

5.3 Next year impairments for different acquisition dates

In Table 8, we fix $t = 12/31/2008$ and we vary acquisition dates of stock Pernod Ricard (whose value is $S_t = 49.26$ at time t). We get then different values of S_{t_a} and corresponding values of Λ_t according to the real evolution of stock Pernod Ricard between t_a and t . For the first acquisition date, $S_{t_a} = 41.98$ and $\Lambda_t = 0$. The probability to recognize an impairment in that case is below 10%, because price went up between t_a and t . For the second acquisition date, as $S_{t_a} = 71.60$ and $\Lambda_t = 22.34$, stock price has gone down and the last impairment occurred due to the significant depreciation criterion. The probability to recognize an impairment next year is very high (above 46%). Note that the choice of the parameters (μ and σ) estimation period is crucial, because it strongly affects the probability to recognize an impairment next year.

Table 8. Results for Pernod Ricard, with $\sigma = 31.38\%$ and $\mu = 7.88\%$, in different scenarios.

Pernod Ricard. $S_t = 49.26$ at $t = 12/31/2008$						
S_{t_a}	Λ_t	$\mathbb{P}_t [J_{t+1}]$	$\mathbb{E}_t [\lambda_{t+1}]$	$VaR(80\%)$	$VaR(95\%)$	$VaR(99.5\%)$
41.98	0	0.0912	1.8944	0	10.9932	19.3704
71.60	22.34	0.4625	4.5728	10.2986	18.9791	26.6504
44.53	0	0.1349	2.3653	0	14.2491	21.9204

5.4 Next year impairments with different trigger levels

We now compare impairment probabilities and potential sizes for two insurers, AXA and Generali, which feature very different impairment triggers: for AXA, we have $\alpha = 0.2$ and $s = 6$ months, where for Generali we have $\alpha = 0.5$ and $s = 36$ months. We can see in Table 9 that the probability to recognize an impairment is much smaller for Generali than for AXA. However, given that an impairment is recognized, the average impairment is likely to be larger for Generali than for AXA.

Remark 4 *For the particular case studied appearing in Table 9, both companies have bought assets today (time t). In this framework, the impairment event of Generali is very easy to write, and so the probability and expectation.*

Indeed, we have $S_t = S_{t_a}$, $\Lambda_t = 0$,

$$J_{t+1} = (S_{t+1} \leq (1 - \alpha)S_{t_a}),$$

$$\mathbb{P}_t [J_{t+1}] = \Phi \left(\frac{\ln(1 - \alpha) - \mu}{\sigma} + \frac{\sigma}{2} \right),$$

and

$$\mathbb{E}_t [\lambda_{t+1}] = -S_t e^{\mu} \Phi \left(\frac{\ln(1 - \alpha) - \mu}{\sigma} - \frac{\sigma}{2} \right) + S_t \Phi \left(\frac{\ln(1 - \alpha) - \mu}{\sigma} + \frac{\sigma}{2} \right).$$

Table 9. Comparison of AXA and Generali impairment triggers: impairment probability and potential severity for 5 different stocks.

	Axa		Generali	
	$\mathbb{P}_t [J_{t+1}]$	$\mathbb{E}_t [\lambda_{t+1} J_{t+1}]$	$\mathbb{P}_t [J_{t+1}]$	$\mathbb{E}_t [\lambda_{t+1} J_{t+1}]$
BNP Paribas	0.3331	21.3545	0.0698	33.8002
Bouygues	0.2762	10.3336	0.011	20.3283
Carrefour	0.2851	8.7095	0.0162	16.4673
Pernod Ricard	0.2374	13.1027	0.00076	32.1938
Total	0.2365	9.7935	0.00069	24.2181

Note that in some other cases, in particular when past impairments are different for AXA and Generali, one might get different results.

6 A proxy method for already impaired equity securities

We have given closed formula for the probability, the expectation and the distribution function of the next-year impairment losses for an equity securities in a particular model. However, these formulas are quite complex and may be hard to extend to more sophisticated model, or to embed into some risk management or investment optimization software. Some insurance practitioners therefore use a simplification of the approach prescribed by the IFRS standards. In this section, we investigate the relevance of considering only the *prolonged* criterion (with an updated parameter) as a proxy. To do that, we look for a new α_1 , parameter of the *significant* criteria, that gives us the same impairment expectation (cf. Theorem 3) but without the *prolonged* criteria. In other words, the new impairment expectation is

$$\begin{aligned}\mathbb{E}_t [\tilde{\lambda}_{t+1}^{\alpha_1}] &= \mathbb{E}_t [(K_t - S_{t+1})^+ \mathbf{1}\{S_{t+1} \leq (1 - \alpha_1)S_{t_a}\}] \\ &= -S_t e^\mu \Phi(-A'(m_t^{\alpha_1})) + K_t \Phi(-A(m_t^{\alpha_1})),\end{aligned}$$

with $m_t^{\alpha_1} = \min(K_t, (1 - \alpha_1)S_{t_a})$.

So we have to solve:

$$\begin{aligned}\mathbb{E}_t [\tilde{\lambda}_{t+1}^{\alpha_1}] &= S_t e^\mu \left(\frac{S_{t_a}}{S_t}\right)^{k_1-1} [\Psi_{-\rho}(C', -D'(K_t)) - \Psi_{-\rho}(C', -D'(m_t))] \\ &\quad + S_t e^\mu [\Psi_\rho(-B', -A'(m_t)) - \Phi(-A'(m_t)) - \Psi_\rho(-B', -A'(K_t))] \\ &\quad + K_t [\Psi_\rho(-B, -A(K_t)) + \Phi(-A(m_t)) - \Psi_\rho(-B, -A(m_t))] \\ &\quad + (K_t - m_t) \left(\frac{S_{t_a}}{S_t}\right)^{k_1-1} [\Phi(-D(m_t)) - \Psi_\rho(-C, -D(m_t))] \\ &\quad - K_t \left(\frac{S_{t_a}}{S_t}\right)^{k_1-1} \Psi_{-\rho}(C, -D(K_t)) + m_t \left(\frac{S_{t_a}}{S_t}\right)^{k_1-1} \Psi_{-\rho}(C, -D(m_t))\end{aligned}\tag{11}$$

Remark 5 *One can note, thanks to the expression of the impairment expectation, when the agent chooses $\alpha_0 \leq \Lambda/S_{t_a}$ as the initial parameter, then $m_t = K_t$ and so the expectation $\mathbb{E}_t[\lambda_{t+1}]$ does not depend on s nor α_0 anymore. It follows that the new α_1 can be taken between 0 and Λ/S_{t_a} . Indeed, $\forall \alpha_1 \leq \Lambda/S_{t_a}$ then $\mathbb{E}_t[\tilde{\lambda}_{t+1}^{\alpha_1}] = \mathbb{E}_t[\lambda_{t+1}]$. And so all those values can be solutions.*

As a consequence, we will impose in the sequel that if $\alpha_0 \leq \Lambda/S_{t_a}$, $\alpha_1 = \alpha_0$.

Moreover, it is possible to verify that, if $\alpha_0 > \Lambda/S_{t_a}$, $\alpha_1 > \Lambda/S_{t_a}$ too.

Expectation sensitivities given previously permit us to know that there is a

unique solution.

6.1 Analytical formula

As for the implicit volatility, it is also possible to give a theoretical formula.

Theorem 7 *For all sets of parameters, we have*

$$\alpha_1 = 1 - \frac{S_t}{S_{t_a}} \exp \left(\left(\mu - \frac{\sigma^2}{2} \right) + \sigma^2 (E_\xi - 1) \right), \quad (12)$$

with:

- $E_\xi = \frac{\partial |C^{(2)} - C^{(1)}|}{\partial \ln S_t}$;
- $C^{(1)} = \frac{\partial \mathbb{E}_t[\lambda_{t+1}]}{\partial \ln S_t}$;
- $C^{(2)} = \frac{\partial^2 \mathbb{E}_t[\lambda_{t+1}]}{\partial (\ln S_t)^2}$.

We obtain a closed-form expression for the new parameter α_1 , as a function of the parameters, and of E_ξ . This last quantity depends on first and second derivatives of the impairment value with respect to S_t (in fact its logarithm), the asset price at time t . So, if the agent owns a sufficient quantity of information to estimate (or to know) E_ξ , she can explicitly determine α_1 .

But this formula is very hard to use in practice, because we need the knowledge of these derivatives. That is why we use numerical methods, as for the implicit volatility.

6.2 Illustration

We have used the numerical MATLAB solver *fzero* in order to find α_1 . The precision of the method was the default precision of the software (i.e. 10^{-6}): we have created a function that returns (original) impairments expectation for a parameters set and another one that returns new impairments expectation for a parameters set. In Figure 3, we show how this new parameter α_1 depends on values of s and (original) α_0 . It is of course increasing in α_1 and s , without any systematic concavity or convexity.

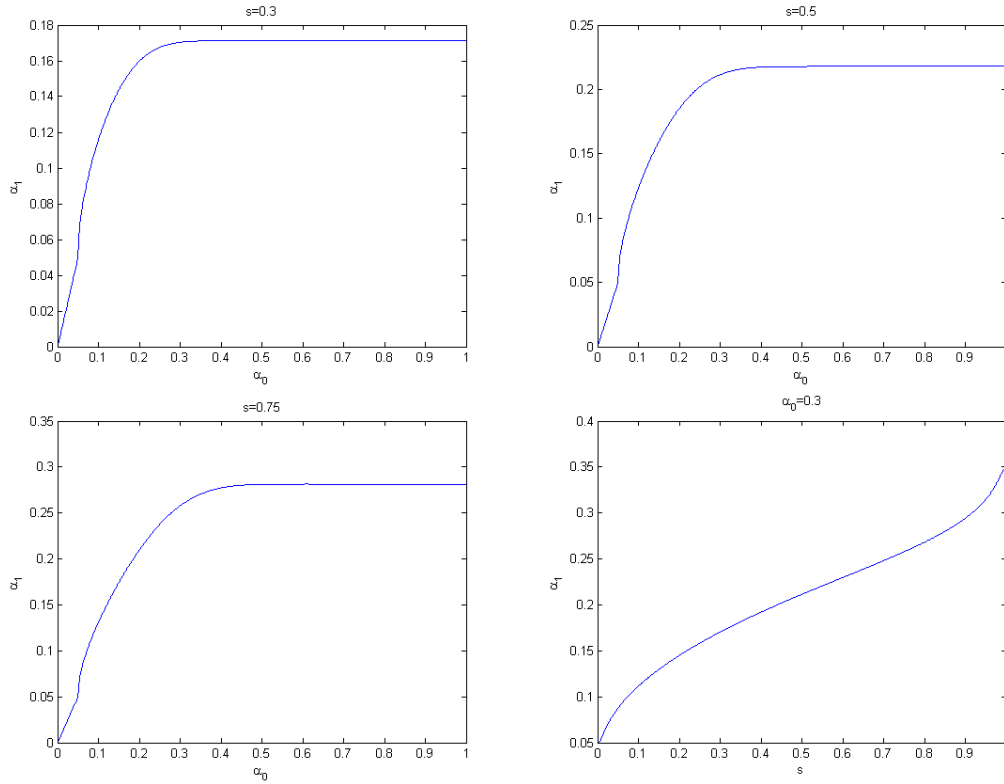


Figure 3. α_1 as a function of α_0 when $s = 0.3$ (top left), $s = 0.5$ (top right), and $s = 0.75$ (bottom left). α_1 as a function of s when $\alpha_0 = 0.3$ (bottom right).

6.3 Quality of this proxy method

The approximation consists in making average impairments identical in both approaches. Here we would like to investigate its quality, through comparison of next year impairment distributions.

Quantiles of next year impairments conditioned to be positive are given in Table 10 for the proxy and for the rigorous approach.

Table 10. Quantiles of next year impairment (conditioned to be positive) with classical criterion and proxy criterion, in the central scenario ($S_t = 95$, $\mu = \ln 0.08$, $\sigma = 0.25$, $S_{t_a} = 100$, $\Lambda = 5$).

$\alpha_0 = 0.3$	$s = 0.3$	$s = 0.5$	$s = 0.75$
$q_{\alpha_0,s}(0.05)$	2.80	3.20	3.65
$q_{\alpha_1}(0.05)$	12.83	16.82	21.33
$q_{\alpha_0,s}(0.5)$	16.83	18.25	20.15
$q_{\alpha_1}(0.5)$	21.13	24.05	27.51
$q_{\alpha_0,s}(0.95)$	36.73	37.66	38.84
$q_{\alpha_1}(0.95)$	38.57	40.04	41.89

One can see that the probability that an impairment occurs is always significantly smaller with the proxy than with the rigorous approach, and that consequently, if an impairment occurs, it is likely to be larger with the proxy than with the rigorous approach. This is in accordance with what we observed in Subsection 5.4 when we compared Axa and Generali impairment trigger levels. The differences are important at all interesting quantile levels for this particular value of $\Lambda = 5$ that corresponds to one sixth of the distance $\alpha_0 S_{t_a}$ between acquisition price S_{t_a} and the significant depreciation threshold $(1 - \alpha_0)S_{t_a}$. We have tested many situations, not presented here for the sake of brevity. In all cases, the conclusion is the same: the quality of the proxy is very bad, except if past impairments are very large. We do not recommend to use it if

$$\frac{\Lambda}{\alpha_0 S_{t_a}} \leq 90\%.$$

Consequently, this proxy might be acceptable only and interesting when $\frac{\Lambda}{\alpha_0 S_{t_a}} \in (0.9; 1)$, which is not going to happen very often. Besides, if this condition were true for one asset, it would be unlikely to be satisfied for all assets, and it would be hard to justify the use of the proxy for some assets but not for the other ones. The conclusion of this section is that the proxy is not suitable for this concrete impairment study, and that one cannot avoid complexity bred by the two impairment criteria in the IFRS framework. This confirms that sophisticated financial analysis is needed to correctly analyze impairment risk.

7 Conclusion

In this paper, we have given the probabilistic characterization of next-year impairment loss of any equity security, in the Black & Scholes framework. We have also studied a proxy that is often used by often practitioners, and found that the quality of this proxy is not good, except when past impairments are large. More generally, our work shows how financial engineering techniques and complex financial option pricing naturally intervene in modern accounting problems. In future work, we plan to extend our results in three different ways: studying the sum of discounted impairments in a multi-period setting, considering a portfolio of equity securities with dependence between stock returns (see Batens (2007)), and testing whether more sophisticated stock price models leads to an effective improvement in the quality of the impairment losses prediction and probabilistic representation.

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Appendix

In the sequel, Φ denotes the c.d.f. of a standard normal distribution, and Ψ_ρ is the bivariate normal distribution function: for all x, y , $\Psi_\rho(x, y) = \mathbb{P}_t[X \leq x, Y \leq y]$ where (X, Y) is a Gaussian vector with standard marginals and correlation ρ .

A Proof of results about the probability that an impairment occurs next year

We would like to evaluate, for S_{t_a} , m_t and K_t , this following quantity:

$$P = \mathbb{P}_t[S_{t+1} \leq m_t] + \mathbb{P}_t \left[\max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a}, S_{t+1} \leq K_t \right] - \mathbb{P}_t \left[\max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a}, S_{t+1} \leq m_t \right].$$

It is possible to quickly retrieve an expression using the drifted Brownian motion $(B_t)_t = \left(\ln \frac{S_t}{S_0} \right)_t$. Indeed, we apply the following property with the previous decomposition and obtain Theorem 1

Proposition 6 *For all real $z \leq a$, for all times $0 < s < t$:*

$$\begin{aligned} & \mathbb{P}_t \left[\max_{t+1-s \leq u \leq t+1} B_u \geq a, B_{t+1} \leq z \right] = \\ & \exp \left(\frac{2(\mu - \frac{\sigma^2}{2})a}{\sigma^2} \right) \left[\Phi \left(\frac{-2a + z - \mu}{\sigma} + \frac{\sigma}{2} \right) \right. \\ & \left. - \Psi_\rho \left(\frac{-a - (1-s)\mu}{\sigma\sqrt{1-s}} - \frac{\sigma\sqrt{1-s}}{2}, \frac{-2a + z - \mu}{\sigma} + \frac{\sigma}{2} \right) \right] \quad (\text{A.1}) \\ & + \left[1 - \Phi \left(\frac{a - (1-s)\mu}{\sigma\sqrt{1-s}} + \frac{\sigma\sqrt{1-s}}{2} \right) \right] \\ & - \Psi_\rho \left(\frac{-a + (1-s)\mu}{\sigma\sqrt{1-s}} - \frac{\sigma\sqrt{1-s}}{2}, \frac{-z + \mu}{\sigma} - \frac{\sigma}{2} \right), \end{aligned}$$

with $\rho = \sqrt{1-s}$.

In the following two subsections, we shall prove this property.

A.1 Proposition 1

Let $X_t = vt + \sigma W_t$, $t \geq 0$ be a drifted Brownian motion. For time t , for some $0 < s < 1$, for all a and z , we would like to express the following quantity:

$$\mathbb{P}_t \left[\max_{t+1-s \leq u \leq t+1} X_u \geq a, X_{t+1} \leq z \right] \quad (\text{A.2})$$

The joint law of a drifted Brownian motion and its running maximum is well known. For example it can be find in Hull (2011), Shreve (2004), Harrison (1985).

We use the following classical result about joint law of a drifted Brownian motion and its running maximum in order to obtain the result:

Lemma A.1 *Let $X_t = vt + \sigma W_t$, $t \geq 0$ be a drifted Brownian motion. For all $a > 0 = X_0$ we have:*

$$\mathbb{P} \left[\max_{0 \leq u \leq t} X_u \geq a, X_t \leq z \right] = \begin{cases} e^{\frac{2\mu a}{\sigma^2}} \Phi \left(\frac{z-2a-vt}{\sigma\sqrt{t}} \right) & , z \leq a \\ \Phi \left(\frac{z-vt}{\sigma\sqrt{t}} \right) - \Phi \left(\frac{a-vt}{\sigma\sqrt{t}} \right) + e^{\frac{2\mu a}{\sigma^2}} \Phi \left(\frac{-a-vt}{\sigma\sqrt{t}} \right) & , z > a. \end{cases} \quad (\text{A.3})$$

The case $a \leq 0$ is simple because $X_0 = 0$, so, $\forall z \in \mathbb{R}$:

$$\mathbb{P} \left[\max_{0 \leq u \leq t} X_u \geq 0, X_t \leq z \right] = \mathbb{P}[X_t \leq z] = \Phi \left(\frac{z - vt}{\sigma\sqrt{t}} \right). \quad (\text{A.4})$$

A.1.1 Application to our problem

In our problem, we focus on the maximum over a period $]t + 1 - s, t + 1]$, for some given s and t . To retrieve the above problem, one can take probabilities conditioned to X_{t+1-s} , it is similar to shift time and space axis in order to make X_{t+1-s} the new origin. Then the barrier value 0 that appears in Equation (A.4) above is from now the value of X_{t+1-s} .

Remark 3 (Notations) *Here above, we assume that we know the value of X_{t+1-s} . For clarity, we denote:*

$$\mathbb{P}_s[A] = \mathbb{P}_t[A/X_{t+1-s}], \quad A \subset \Omega$$

and we shall use

$$\mathbb{P}_s[A]_{|X_{t+1-s}=x} = \mathbb{P}_t[A/X_{t+1-s} = x], \quad A \subset \Omega.$$

One can then easily get

- for $a > X_{t+1-s}$,

$$\mathbb{P}_s \left[\max_{t+1-s \leq u \leq t+1} X_u \geq a, X_{t+1} \leq z \right] = \begin{cases} e^{\frac{2\mu(a-X_{t+1-s})}{\sigma^2}} \Phi \left(\frac{z-2a+X_{t+1-s}-vs}{\sigma\sqrt{s}} \right) & , z \leq a \\ \Phi \left(\frac{z-X_{t+1-s}-vs}{\sigma\sqrt{s}} \right) \\ -\Phi \left(\frac{a-X_{t+1-s}-vs}{\sigma\sqrt{s}} \right) \\ +e^{\frac{2\mu(a-X_{t+1-s})}{\sigma^2}} \Phi \left(\frac{-a+X_{t+1-s}-vs}{\sigma\sqrt{s}} \right) & , z > a. \end{cases} \quad (\text{A.5})$$

- For $a \leq X_{t+1-s}$, $\forall z \in \mathbb{R}$, we have

$$\begin{aligned} \mathbb{P}_s \left[\max_{t+1-s \leq u \leq t+1} X_u \geq a, X_{t+1} \leq z \right] &= \mathbb{P}_s \left[\max_{t+1-s \leq u \leq t+1} X_u \geq X_{t+1-s}, X_{t+1} \leq z \right] \\ &= \Phi \left(\frac{z - X_{t+1-s} - vs}{\sigma\sqrt{s}} \right). \end{aligned} \quad (\text{A.6})$$

But we would like to get rid of this conditioning. So the next step is to take the integral among all possible values of X_{t+1-s} .

A.1.2 Conditional law and integration

Explicitly, we have to evaluate, for all $a \in \mathbb{R}$ and $z \leq a$:

$$\begin{aligned} &\mathbb{P}_t \left[\max_{t+1-s \leq u \leq t+1} X_u \geq a, X_{t+1} \leq z \right] \\ &= \int_{x=-\infty}^{+\infty} \mathbb{P}_s \left[\max_{t+1-s \leq u \leq t+1} X_u \geq a, X_{t+1} \leq z \right]_{|X_{t+1-s}=x} d\mathbb{P}_t [X_{t+1-s} \leq x] \\ &= \int_{x=-\infty}^a \mathbb{P}_s \left[\max_{t+1-s \leq u \leq t+1} X_u \geq a, X_{t+1} \leq z \right]_{|X_{t+1-s}=x} d\mathbb{P}_t [X_{t+1-s} \leq x] \quad (\text{A.7}) \\ &+ \int_{x=a}^{+\infty} \mathbb{P}_s \left[\max_{t+1-s \leq u \leq t+1} X_u \geq a, X_{t+1} \leq z \right]_{|X_{t+1-s}=x} d\mathbb{P}_t [X_{t+1-s} \leq x] \\ &= \Xi_1(a, z) + \Xi_2(a, z), \end{aligned}$$

where the expression of $d\mathbb{P} [X_{t+1-s} \leq x]$, $x \in \mathbb{R}$ is as follows:

$$d\mathbb{P}_t [X_{t+1-s} \leq x] = \frac{1}{\sigma\sqrt{1-s}} \varphi \left(\frac{x - v(1-s)}{\sigma\sqrt{1-s}} \right) dx.$$

Then it is possible to use Proposition 2.1 in Chuang (1996) (p.83) to evaluate both integrals. Define $\rho = \sqrt{1-s}$. We first introduce the following intermediate variables:

- $c = -2\mu/\sigma^2$,
- $\delta_1 = v(1 - s)$,
- $\eta_1 = \sigma\sqrt{1 - s}$,
- $\delta_2 = 2a + vs - z$,
- and $\eta_2 = \sigma\sqrt{s}$.

We can now recognize the result of Chuang (1996):

$$\Xi_1(a, z) = \exp\left(\frac{2va}{\sigma^2}\right) \left[\Phi\left(\frac{-v - 2a + z}{\sigma}\right) - \Psi_\rho\left(\frac{-a - v(1 - s)}{\sigma\sqrt{1 - s}}, \frac{-v - 2a + z}{\sigma}\right) \right].$$

We do the same with the following intermediate variables:

- $c = 0$,
- $\delta_1 = v(1 - s)$,
- $\eta_1 = \sigma\sqrt{1 - s}$,
- $\delta_2 = z - vs$,
- and $\eta_2 = \sigma\sqrt{s}$.

We obtain:

$$\Xi_2(a, z) = \left[1 - \Phi\left(\frac{a - v(1 - s)}{\sigma\sqrt{1 - s}}\right) \right] - \Psi_\rho\left(\frac{-a + v(1 - s)}{\sigma\sqrt{1 - s}}, \frac{v - z}{\sigma}\right).$$

B Proof of results about expected value of next year impairment

Thanks to the decomposition introduced in the Property 2 p.11, we are able to use results about some exotic option, the *Rear-End up-and-out Put Option*. This option is studied in Carr and Chou (1997), Cox and Rubinstein (1985), Carr (1995), Hui (1997) for example. Here after, we present some of its characteristics.

B.1 Rear-End up-and-out Put Option

The barrier of a rear-end put option exists from an intermediate time t between the option time start 0 and the option maturity T . The value of the option at this intermediate time is the value of a up-and-out put option with maturity the time that left $T - t$ (it will be s in our study).

- Its price is given by

$$\begin{aligned}
P_{2uo} &= Ke^{-rT} \Psi_{\rho}(-B(1-s), -A(T)) - S_0 \Psi_{\rho}(-B'(1-s), -A'(T)) \\
&\quad - \left(\frac{b}{S_0}\right)^{k_1-1} Ke^{-rT} \Psi_{-\rho}(C(1-s), -D(T)) \\
&\quad + \left(\frac{b}{S_0}\right)^{k_1-1} S_0 \Psi_{-\rho}(C'(1-s), -D'(T)),
\end{aligned}$$

where

$$\begin{aligned}
\cdot A(t) &= \frac{\ln(S_0/K)+rt}{\sigma\sqrt{t}} - \frac{\sigma\sqrt{t}}{2}, A'(t) = A + \sigma\sqrt{t}, \\
\cdot B(t) &= \frac{\ln(S_0/b)+rt}{\sigma\sqrt{t}} - \frac{\sigma\sqrt{t}}{2}, B'(t) = B + \sigma\sqrt{t}, \\
\cdot C(t) &= \frac{\ln(b/S_0)+rt}{\sigma\sqrt{t}} - \frac{\sigma\sqrt{t}}{2}, C'(t) = C + \sigma\sqrt{t}, \\
\cdot D(t) &= \frac{\ln(b^2/S_0K)+rt}{\sigma\sqrt{t}} - \frac{\sigma\sqrt{t}}{2}, D'(t) = D + \sigma\sqrt{t}, \\
\cdot k_1 &= \frac{2\mu}{\sigma^2},
\end{aligned}$$

and $\rho = \sqrt{t/T}$.

- Expectation of its payoff under P measure is

$$\begin{aligned}
P_{2uo} &= K \Psi_{\rho}(-B(1-s), -A(T)) - S_0 e^{\mu T} \Psi_{\rho}(-B'(1-s), -A'(T)) \\
&\quad - \left(\frac{b}{S_0}\right)^{k_1-1} K \Psi_{-\rho}(C(1-s), -D(T)) \\
&\quad + \left(\frac{b}{S_0}\right)^{k_1-1} S_0 e^{\mu T} \Psi_{-\rho}(C'(1-s), -D'(T)),
\end{aligned}$$

where

$$\begin{aligned}
\cdot A(t) &= \frac{\ln(S_0/K)+\mu t}{\sigma\sqrt{t}} - \frac{\sigma\sqrt{t}}{2}, A'(t) = A + \sigma\sqrt{t}, \\
\cdot B(t) &= \frac{\ln(S_0/b)+\mu t}{\sigma\sqrt{t}} - \frac{\sigma\sqrt{t}}{2}, B'(t) = B + \sigma\sqrt{t}, \\
\cdot C(t) &= \frac{\ln(b/S_0)+\mu t}{\sigma\sqrt{t}} - \frac{\sigma\sqrt{t}}{2}, C'(t) = C + \sigma\sqrt{t}, \\
\cdot D(t) &= \frac{\ln(b^2/S_0K)+\mu t}{\sigma\sqrt{t}} - \frac{\sigma\sqrt{t}}{2}, D'(t) = D + \sigma\sqrt{t}, \\
\cdot k_1 &= \frac{2\mu}{\sigma^2},
\end{aligned}$$

and $\rho = \sqrt{t/T}$.

B.2 Application

We can now directly derive an expression of

$$\mathbb{E}_t [X_{t+1}] = \mathbb{E}_t \left[(K_t - S_{t+1})^+ \mathbf{1} \left\{ \max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a} \right\} \right]. \quad (\text{B.1})$$

Proposition 4 *We have*

$$\begin{aligned} \mathbb{E}_t [X_{t+1}] &= K_t \Psi_\rho(-B, -A(K_t)) - S_t e^\mu \Psi_\rho(-B', -A'(K_t)) \\ &\quad - \left(\frac{S_{t_a}}{S_t} \right)^{k_1-1} K_t \Psi_{-\rho}(C, -D(K_t)) + \left(\frac{S_{t_a}}{S_t} \right)^{k_1-1} S_t e^\mu \Psi_{-\rho}(C', -D'(K_t)), \end{aligned}$$

where

- $A(K_t) = \frac{\ln(S_t/K_t) + \mu}{\sigma} - \frac{\sigma}{2}$, $A'(K_t) = A(K_t) + \sigma$,
- $B = \frac{\ln(S_t/S_{t_a}) + \mu(1-s)}{\sigma\sqrt{(1-s)}} - \frac{\sigma\sqrt{(1-s)}}{2}$, $B' = B + \sigma\sqrt{(1-s)}$,
- $C = \frac{\ln(S_{t_a}/S_t) + \mu(1-s)}{\sigma\sqrt{(1-s)}} - \frac{\sigma\sqrt{(1-s)}}{2}$, $C' = C + \sigma\sqrt{(1-s)}$,
- $D(K_t) = \frac{\ln(S_{t_a}^2/S_t K_t) + \mu}{\sigma} - \frac{\sigma}{2}$, $D'(K_t) = D(K_t) + \sigma$,
- $k_1 = \frac{2\mu}{\sigma^2}$

and $\rho = \sqrt{(1-s)}$.

Terms Y_{t+1} and Z_{t+1} are both easy to compute. In fact we only have to get rid of the indicator on $\{S_t \leq (1-\alpha)S_{t_a}\}$ to make known expressions appear. The previously used variable $m_t = \min(K_t, (1-\alpha)S_{t_a})$ is involved in the next computations.

For Y_{t+1} , $\forall K_t, \alpha$, we have

$$Y_{t+1} = (K_t - S_{t+1})^+ \mathbf{1} \{S_{t+1} \leq (1-\alpha)S_{t_a}\} = (m_t - S_{t+1})^+ + (K_t - m_t) \mathbf{1} \{S_{t+1} \leq m_t\}$$

and we obtain the following proposition.

Proposition 5 *We have*

$$\begin{aligned} \mathbb{E}_t [Y_{t+1}] &= P(S_t, t+1, m_t) + \mathbb{E}_t [(K_t - m_t) \mathbf{1} \{S_{t+1} \leq m_t\}] \\ &= -S_t e^\mu \Phi(-A'(m_t)) + K_t \Phi(-A(m_t)). \end{aligned} \quad (\text{B.2})$$

For the last term, we have

$$\begin{aligned} Z_{t+1} &= (K - S_{t+1})^+ \mathbf{1} \left\{ \max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a} \right\} \mathbf{1} \{S_{t+1} \leq (1-\alpha)S_{t_a}\} \\ &= (m - S_{t+1})^+ \mathbf{1} \left\{ \max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a} \right\} \\ &\quad + (K - m) \mathbf{1} \left\{ \max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a} \right\} \mathbf{1} \{S_{t+1} \leq m\}, \end{aligned}$$

and we obtain the following proposition.

Proposition 6 *We have*

$$\begin{aligned}
\mathbb{E}_t [Z_{t+1}] &= K_t \Psi_\rho(-B, -A(m_t)) - S_t e^\mu \Psi_\rho(-B', -A'(m_t)) \\
&\quad - \left(\frac{S_{t_a}}{S_t}\right)^{k_1-1} m_t \Psi_{-\rho}(C, -D(m_t)) + \left(\frac{S_{t_a}}{S_t}\right)^{k_1-1} S_t e^\mu \Psi_{-\rho}(C', -D'(m_t)) \\
&\quad - (K_t - m_t) \left(\frac{S_{t_a}}{S_t}\right)^{k_1-1} \{\Phi(-D(m_t)) - \Psi_\rho(-C, -D(m_t))\},
\end{aligned} \tag{B.3}$$

where

- $A(m_t) = \frac{\ln(S_t/m_t) + \mu}{\sigma} - \frac{\sigma}{2}$, $A'(m_t) = A(m_t) + \sigma$,
- $B = \frac{\ln(S_t/S_{t_a}) + \mu(1-s)}{\sigma\sqrt{(1-s)}} - \frac{\sigma\sqrt{(1-s)}}{2}$, $B' = B + \sigma\sqrt{(1-s)}$,
- $C = \frac{\ln(S_{t_a}/S_t) + \mu(1-s)}{\sigma\sqrt{(1-s)}} - \frac{\sigma\sqrt{(1-s)}}{2}$, $C' = C + \sigma\sqrt{(1-s)}$,
- $D(m_t) = \frac{\ln(S_{t_a}^2/S_t m_t) + \mu}{\sigma} - \frac{\sigma}{2}$, $D'(m_t) = D(m_t) + \sigma$,
- $k_1 = \frac{2\mu}{\sigma^2}$,

and $\rho = \sqrt{(1-s)}$.

C Sensitivities of impairment probability and expectation

The following partial derivatives can be obtained and are used in the analysis:

$$\frac{\partial}{\partial x} \Psi_\rho(x, y) = \exp\left(-\frac{x^2}{2\sqrt{1-\rho^2}}\right) \Phi\left(\frac{y-\rho x}{\sqrt{1-\rho^2}}\right), \tag{C.1}$$

$$\frac{\partial}{\partial y} \Psi_\rho(x, y) = \exp\left(-\frac{y^2}{2\sqrt{1-\rho^2}}\right) \Phi\left(\frac{x-\rho y}{\sqrt{1-\rho^2}}\right), \tag{C.2}$$

$$\frac{\partial}{\partial a} \Psi_\rho(x(a), y) = \exp\left(-\frac{x(a)^2}{2\sqrt{1-\rho^2}}\right) \Phi\left(\frac{y-\rho x(a)}{\sqrt{1-\rho^2}}\right) \times x'(a), \tag{C.3}$$

$$\frac{\partial}{\partial a} \Psi_\rho(x, y(a)) = \exp\left(-\frac{y(a)^2}{2\sqrt{1-\rho^2}}\right) \Phi\left(\frac{x-\rho y(a)}{\sqrt{1-\rho^2}}\right) \times y'(a), \tag{C.4}$$

$$\begin{aligned} \frac{\partial}{\partial a} \Psi_\rho(x(a), y(a)) &= \exp\left(-\frac{x(a)^2}{2\sqrt{1-\rho^2}}\right) \Phi\left(\frac{y(a) - \rho x(a)}{\sqrt{1-\rho^2}}\right) \times x'(a) \\ &+ \exp\left(-\frac{y(a)^2}{2\sqrt{1-\rho^2}}\right) \Phi\left(\frac{x(a) - \rho y(a)}{\sqrt{1-\rho^2}}\right) \times y'(a), \end{aligned} \quad (\text{C.5})$$

$$\frac{\partial}{\partial \rho} \Psi_\rho(x, y) = \frac{\rho}{1-\rho^2} [\Psi_\rho(x, y) - 1], \quad (\text{C.6})$$

and

$$\begin{aligned} \frac{\partial}{\partial \rho} \Psi_\rho(x(\rho), y(\rho)) &= \frac{\rho}{1-\rho^2} [\Psi_\rho(x(\rho), y(\rho)) - 1] \\ &+ \exp\left(-\frac{x(\rho)^2}{2\sqrt{1-\rho^2}}\right) \Phi\left(\frac{y(\rho) - \rho x(\rho)}{\sqrt{1-\rho^2}}\right) \times x'(\rho) \\ &+ \exp\left(-\frac{y(\rho)^2}{2\sqrt{1-\rho^2}}\right) \Phi\left(\frac{x(\rho) - \rho y(\rho)}{\sqrt{1-\rho^2}}\right) \times y'(\rho). \end{aligned} \quad (\text{C.7})$$

D Proof of results about the distribution of next year impairment

We decompose the expression of the cumulative distribution function to obtain:

$$\begin{aligned} \mathbb{P}_t[\lambda_{t+1} \leq l] &= \mathbb{P}_t[\lambda_{t+1} \leq l, \lambda_{t+1} = 0] + \mathbb{P}_t[\lambda_{t+1} \leq l, \lambda_{t+1} \neq 0] \\ &= \mathbb{P}_t[\lambda_{t+1} = 0] + \mathbb{P}_t[\lambda_{t+1} \leq l, \lambda_{t+1} \neq 0]. \end{aligned} \quad (\text{D.1})$$

Then, we have, for $K_t - l < m_t$,

$$\mathbb{P}_t[\lambda_{t+1} \leq l, \lambda_{t+1} \neq 0] = \mathbb{P}_t[J_{t+1}] - \mathbb{P}_t[S_{t+1} \leq K_t - l].$$

Consequently, $\forall K_t - m_t < l \leq K_t$, we have

$$\mathbb{P}_t[\lambda_{t+1} \leq l] = \Phi(A(K_t - l)). \quad (\text{D.2})$$

The second step is to study what happens when $l \leq K_t - m_t$. Obviously, if $m_t = K_t$, then l can only be equal to zero, and then $\mathbb{P}_t[\lambda_{t+1} \leq l] = 1 - \mathbb{P}_t[J_{t+1}]$. Else, if $m_t = (1 - \alpha)S_{t_a}$, then we have

$$\{K_t - l \leq S_{t+1}\} \cap \{S_{t+1} \leq (1 - \alpha)S_{t_a}\} = \emptyset$$

and

$$\begin{aligned}
\mathbb{P}_t[\lambda_{t+1} \leq l, \lambda_{t+1} \neq 0] &= \mathbb{P}_t \left[K_t - l \leq S_{t+1} \leq K_t, \max_{t+1-s \leq u \leq t+1} S_u \leq S_{t_a} \right] \\
&= \mathbb{P}_t [S_{t+1} \leq K_t] - \mathbb{P}_t [S_{t+1} \leq K_t - l] \\
&+ \mathbb{P}_t \left[\max_{t+1-s \leq u \leq t+1} S_u > S_{t_a}, S_{t+1} \leq K_t - l \right] \\
&- \mathbb{P}_t \left[\max_{t+1-s \leq u \leq t+1} S_u > S_{t_a}, S_{t+1} \leq K_t \right].
\end{aligned}$$

We then use previous results about exotic options to conclude:

$$\begin{aligned}
\mathbb{P}_t[\lambda_{t+1} \leq l, \lambda_{t+1} \neq 0] &= \Phi(A(K_t - l)) - \Phi(A(K_t)) \\
&+ \left(\frac{S_{t_a}}{S_t} \right)^{k_1 - 1} [\Psi_\rho(C, D(K_t)) - \Psi_\rho(C, D(K_t - l))] \\
&+ \Psi_\rho(B, A(K_t)) - \Psi_\rho(B, A(K_t - l)).
\end{aligned}$$

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